



TECHNCIAL NOTE no.: 52					
Product:	GPS to CAN v2 module				
Part number:	s/r				
То:	Cupra Leon VZ TCR				
Date:	23/05/2024				

Dear customer,

The GPS module supplied with the 7" ADU display (currently only on CUPRA Leon VZ), needs a Firmware update to improve the accuracy of the internal accelerometers. Due to a hardware change of the internal components, there were too much noise on the accelerometer signals and the axis directions were opposite to the old GPS module making difficult the lap comparison.



To solve this issue, customers who has this GPS to CAN V2 module (Leon VZ) must upgrade the FW version using the Software LightClientSetup_2_0.exe and gps2__fw4_0.bin file.

SW and FW files are available on the VW Group Motorsport online platform download area at the path "PROJECTS & SOFTWARE / SW_PROJECTS_2024 / GPS FW / CUPRA LEON VZ".

GPS module update process:

- 1. Install LightClientSetup_2_0.exe in your computer.
- 2. Connect the display CAN interface or the Peak Can Interface to the diagnostic connector and switch on Main Power supply.
- 3. Open the LightClient Software and choose "**auto**" as CAN bit rate.
- 4. In the Devices zone, choose the **gps2** module. Double click on it.
- 5. Click on the Upgrade button and select the file "gps2__fw4_0.bin"
- 6. Wait until the firmware update is done.
- 7. In the properties zone, activate the "**High rate IMU output**" square box. Then select the ID number **0x408 Standard** on the "Output CAN ID".
- On the IMU config box, select the orientation "Custom" and change the orientation of the three axis X (Back), Y (Left) and Z (Up).

IMPORTANT: If a v1 GPS module (Audi or CUPRA Leon Competición with 5" ADU display) is updated with this FW, the GPS may not work properly.





追 Ecumaster Light	Client:	1 Mbps													-		\times
Devices										A	ll frames						
Туре	Rev	Serial number	Firmware	Comme	nt	Info			Refresh	1	ID	DLC	Bytes	Freq	Count	Tx	1
ADU	G	316-2404-00207	FW 78.0								000h	2	01 15	58,4 Hz	7162		
> gps2	E	534-2325-00258	FW 4.0			Out: 400-404, 408-409			Set comment		018h	8	00 00 00 00 00 00 00 00 00	100,2 Hz	14323		
keypad 6x2 RGB	V_03	N/A	FW 2.25			In: 000, 215, 315, 415, 595,	, 695 Out: 195, 7	715		-	020h	3	00 00 00	10,0 Hz	1430		
									User manual		040h	8	00 04 03 02 00 0B 00 00	200,3 Hz	28647		
				_					Upgrade	n T	045h	8	00 00 00 00 00 00 00 00 00	10,3 Hz	1432		
Devices							opgroue		110h	8	12 00 00 00 00 00 00 00 00	99,7 Hz	14282				
									More		111h	8	00 00 00 00 00 00 00 00 00	100,6 Hz	14284		
											112h	8	00 00 00 00 00 00 00 00	20,0 Hz	2858		
Descention					10	Channels					113h	8	00 00 00 00 00 00 00 00 00	19,9 Hz	2857		
Properties						Ecumaster format			^		114h	8	F3 FF F6 FF 00 00 00 00	99,3 Hz	14283		
Ecumaster output		1				Latitude	41,5059005	۰			117h	8	F2 00 D5 FF 8A FC 00 00	99,3 Hz	11426		
Enable]				Longitude	1,8990732	•			196h	8	99 06 00 00 00 00 00 00 00	19,6 Hz	2865		
Output CAN ID	0x	400 Standard			_	Speed	0,11	km/h			197h	8	00 00 00 00 00 00 00 00	111,1 Hz	16659		
High rate IMU outp	ut					Height	124	m			1F0h	8	00 01 01 01 01 01 00 00	111,6 Hz	14316		
Enable	2]				Satellites	6				215h	8	40 00 04 40 00 00 00 00 00	10,3 Hz	1432		
Output CAN ID	0x	408 Standard				GPS status	GPS-3D				222h	8	36 32 64 FA 4C 64 64 00	123,4 Hz	14317		
Format M output						Heading motion	60	۰			24Ch	8	0B 00 00 00 00 00 00 00 00	111,1 Hz	14316		
Enable]				X ang rate	0,29	°/s			400h	8	18 BD 4C 3D 01 21 C6 8C	25,6 Hz	3578		
Format LR output						Y ang rate	0,89	°/s			401h	8	00 03 00 7C 00 06 00 1C	25,6 Hz	3578		
Enable]				Z ang rate	-0,38	°/s			402h	8	00 3C 00 00 00 1D 00 59	25,6 Hz	3578		
Navigation config						X acceleration	0,03	g			403h	8	FF DA 00 03 00 02 00 65	25,8 Hz	3578		
Navigation systems	GF	S+Galileo+BeiDo	u+GLONASS	5	\sim	Y acceleration	0,02	g			404h	8	18 05 17 0B 02 2C EB 85	25,6 Hz	3578		
Static hold config						Z acceleration	1,01	g			408h	8	00 19 00 5D FF D9 00 00	202,1 Hz	28629		
Enable		1				UTC year	2024				409h	8	00 02 00 02 00 65 00 00	202,1 Hz	28629		
Distance threshold	10	m				UTC month	5				410h	8	00 00 00 00 00 00 00 00 00	58,3 Hz	7162		`
Speed threshold	3,6	i0 km/h				UTC day	23				<						>
IMU config						UTC hour	11							Clear	trace	Save t	race
Orientation	Cu	ustom			_	UTC minute	2										
X direction	Ba	ck				UTC second	44			Т	an an it				•	II +	×
V direction	Le	ft				UTC milisecond	920			11	ansmit		• -				
7 direction	Ur					GPS frame index	0				ID	DLC	Bytes	Freq	Count	Comm	lent
Acceleration filter	46	, Н7				Empty frame index	0										
Acceleration linter	40	112				High rate IMU											
				HR X ang rate	0,25	°/s											
Properties			HR Y ang rate	0,93	°/s												
Fioperties				HR Z ang rate	-0,39	*/s											
						HR X accel	0,02	g									
L						HR Y accel	0,02	g									
		Tools				HR Z accel	1,01	g									

Wintax properties:

After doing the GPS module FW update, a new FFT Low pass filter at 20Hz on the G_X, G_Y and **G_Z** channels must be activated on Wintax, as shown below on the Graph Properties window:

Ele Edit Vew Graph Help Image: Sections Report Sections Report Script Image: Sections Report Script Window Options Vindow Options Image: Section Sectin Sectin Section Secting Sectin Section Secting Section												
Image: Sections Report Script Window Options												
Options Event Sections Report Script												
Window Options	Options Event Sections Report Script											
Window Options												
Custom Color Window Graph Border Grid Cursor Styles Layout Y Scales Text mode X Axis Mode Double X Axis Time Scale Real Time Settings Cursor Value mode												
L Custom Vertical V Manual Auto V Time V Relative V Default Right V												
Graphs Options												
Label Color Style Unit Format Grid Dataset Show Local Min Max Bottom (%) Too (%) Group Mode Line Alarm Condition Filter S	show											
G_X_ADU ■ Default ☑ Auto Off All ☑ ✓ -1.8 1.8 50 100 - ▼ Auto Off Default - Off [
G_X ■ Default ♥ Auto Off All □ ♥ -1.8 1.8 50 100 - ♥ Auto Off Default - FFTLow Pass [
G_X_Bosch												
Default ☑ Auto Off All ☑ -200 200 0 100 - ☑ Auto Off Default - Off [
G_Y_ADU ■ Default ♥ Auto Off All ♥ ♥ -1.8 1.8 0 50 - ♥ Auto Off Default - Off [
G Y Default ♥ Auto Off All □ ♥ -1.8 1.8 0 50 - ♥ Auto Off Default - FFT Low Pass [
G_Y_Bosch ■ Default 🗹 Auto Off □ 🔽 -1.8 1.8 0 50 - 🔽 Auto Off Default - Off [

Туре		Length (ms)	Freq1 (Hz)	Freq2 (Hz)	
FFT Low Pass	•	0	20	0	